

注塑用机械手 TAKE-OUT ROBOT

MEWE-120
MEWE-120s

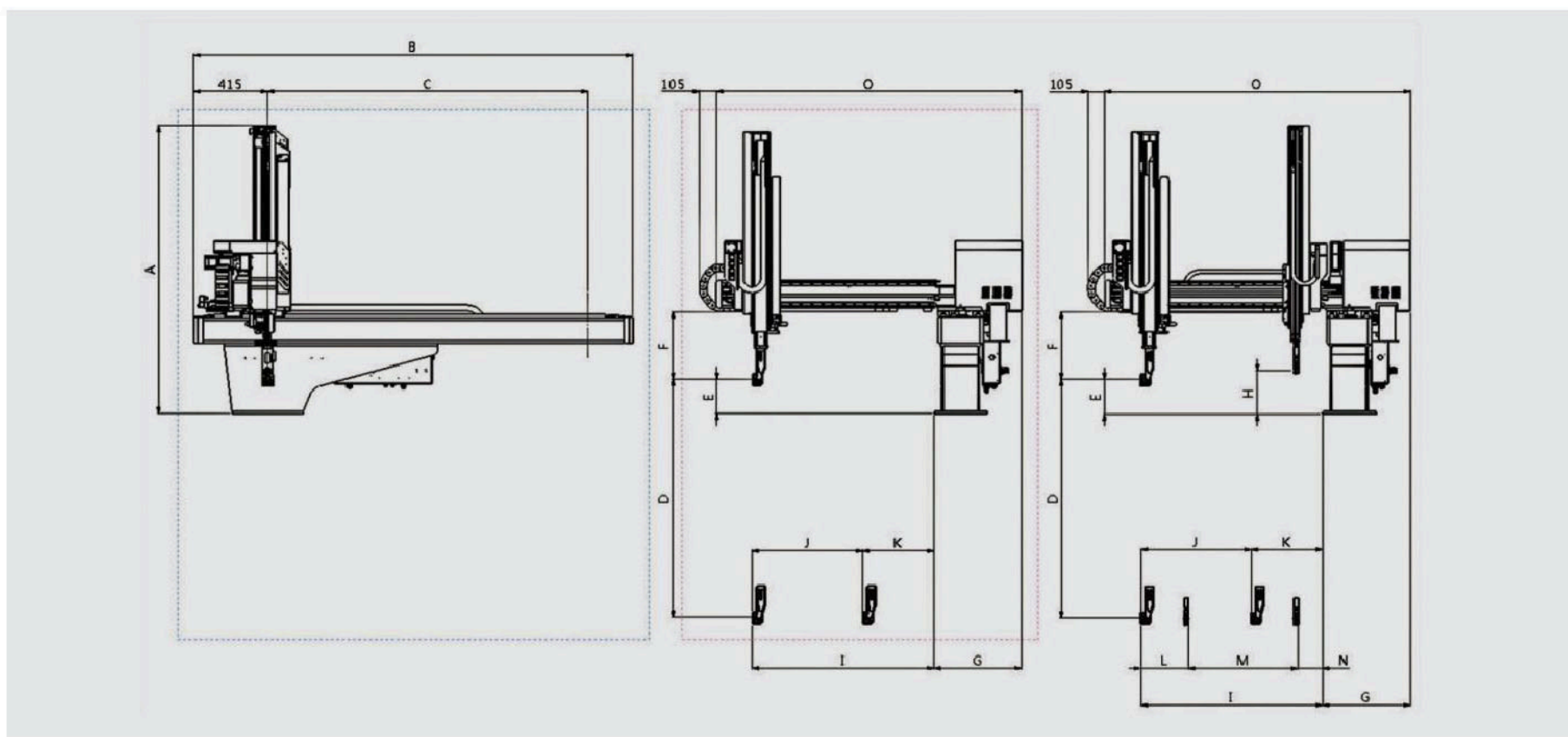


标准功能 STANDARD FUNCTION

- 装箱动作 (各轴256点)
Packaging motion (Max. 256 points)
- 自由装箱点 (115点×2处)
Free packaging motion (115points×2stage)
- 取出侧前进姿势控制
Forward and rotate at removing side
- 走行途中姿势
Posture control during traverse
- 落下测下降途中姿势
Posture midway descent at release side
- 顶针连动
Ejector link
- 不良品排出回路
Defective product reject circuit
- 初期不良品排出回路
Initial defective product reject circuit
- 取出下降待机
Delayed arm descent
- 胶口途中开放 (去程, 返程)
Midway runner release (Move, Revert)
- 水口模内开放
Runner release within mold
- 吸着确认单元 (2回路)
Additional vacuum sensing unit (2 circuit)
- 横走行待机
Delayed traverse
- 滑移取出回路
Undercut extract circuit
- 输送带启动信号
Start signal of conveyor
- 内部存储记忆 (最大100种类型)
Internal memory (for Max 100 molds)
- 设定值锁定功能
Lock function of setting value
- 固定可动切换
Extraction from fixed mold
- 2国语言切换 (中文, 英文)
Two language exchange (Chinese/English)

型式 MODEL 单位 UNIT MEWE-120 MEWE-120s

电源 Power Source	V	AC 220 ± 10% 50/60Hz	
最大消费电力 Max Power Consumption	KW	1.9	2.8
使用气压 Air Pressure	Mpa	0.5~0.7	
空气消费量 Air Consumption	NI/cycle	18	
驱动方式 Drive System	---	伺服马达 / AC Servo Motor	
姿势 (气缸) Posture (Air Cylinder)	---	90°固定 / 90°Fixed	
■ 气缸推力 (气压0.49MPa时) Air Cylinder Driving Force (Air Pressure at 0.49MPa)			
最大可搬重量 Max.Load	Kg	5【含夹具重量 / Incl Chuck Weight】	
姿势力矩 Posture Torque	N·m	10.1	
■ 行程 Stroke			
主臂上下 Main-arm Vertical	mm	1200/1400	1200/1400
副臂上下 Sub-arm Vertical	mm	---	1250/1450
前后(主臂,副臂) Crosswise (M,S)	mm	主臂/M 160~1020	主臂/M 395~1020 副臂/S 140~760
走行 Traverse	mm	1800	
■ 本体重量 Net Weight			
本体 Main Body	Kg	450	
操作盒 Pendant	Kg	1.6	



外形尺寸 OUTER DIMENSIONS

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A	总高 Overall height	1560(1680)mm	1600(1720)mm
B	总长 Overall length	2470mm	
C	走行行程 Traverse stroke	1800 mm	
D	主臂上下行程 Main-arm vertical stroke	1200 (1400)mm	
E	主臂上下待机 Main-arm vertical standby	205mm	
F	夹具安装有效空间 Bottom of crosswise to chuck mount position	410mm	
G	底座里侧面-箱体末端 Base side face-Box end	495 mm	
H	副臂上下待机 Sub-arm Vertical standby	---	250 mm
I	主臂前进最大值 Main-arm reach max	1020 mm	
J	主臂前进最大行程 Main-arm crosswise stroke max	855 mm	620 mm
K	主臂前后待机最小值 Main-arm crosswise standby min	165 mm	395 mm
L	主副臂接近最小值 Main/Sub-arm proximity min	---	260 mm
M	副臂前进最大行程 Sub-arm crosswise stroke max	---	620 mm
N	副臂前后待机最小值 Sub-arm crosswise standby min	---	140 mm
O	前后臂末端-箱体末端 Crosswise arm end-Box end	1715 mm	

- 当机械手为三轴时，尺寸D是1200mm时，尺寸A为1560mm
- When the manipulator is triaxial and D is 1200, dimension A is 1560.

- 当机械手为五轴时，尺寸D是1200mm时，尺寸A为1600mm
- When the manipulator is five axis and D is 1200, dimension A is 1600.

- 当机械手为三轴时，尺寸D是1400mm时，尺寸A为1680mm
- When the manipulator is triaxial and D is 1400, dimension A is 1680.

- 当机械手为五轴时，尺寸D是1400mm时，尺寸A为1720mm
- When the manipulator is five axis and D is 1400, dimension A is 1720.

选项功能 OPTION FUNCTION

- ◆ 夹具内剪刀回路
Air nipper in chuck circuit
- ◆ NT剪切·可动侧
NT gate cutting on crossmember of moving
- ◆ 吸着确认4回路
Additional vacuum sensing unit (4 circuits)
- ◆ 制品夹取4回路
Product gripping 4 circuits
- ◆ 上升途中闭模
Mold close during ascend
- ◆ 回转单元
Rotation unit
- ◆ 顶针后退连动
Ejector return link
- ◆ 欧规12
EUROMAP12
- ◆ 欧规67
EUROMAP 67