



# 牛头式三轴伺服机械手

King Size Three-Axis Servo Driven Robots

MBW-170

# 注塑用机械手 TAKE-OUT ROBOT

## MBW-170

### 标准功能 STANDARD FUNCTION

装箱动作 (各轴256点)  
Packaging motion (Max. 256 points)

自由装箱点 (115点×2处)  
Free packaging motion (115points×2stage)

取出侧前进姿势控制  
Forward and rotate at removing side

走行途中姿势  
Posture control during traverse

落下测下降途中姿势  
Posture midway descent at release side

顶针连动  
Ejector link

不良品排出回路  
Defective product reject circuit

初期不良品排出回路  
Initial defective product reject circuit

取出下降待机  
Delayed arm descent

胶口途中开放 (去程, 返程)  
Midway runner release (Move, Revert)

水口模内开放  
Runner release within mold

吸着确认单元 (2回路)  
Additional vacuum sensing unit (2 circuit)

横走行待机  
Delayed traverse

滑移取出回路  
Undercut extract circuit

输送带启动信号  
Start signal of conveyor

内部存储记忆 (最大100种类型)  
Internal memory (for Max 100 molds)

设定值锁定功能  
Lock function of setting value

固定可动切换  
Extraction from fixed mold

2国语言切换 (中文, 英文)  
Two language exchange (Chinese/English)

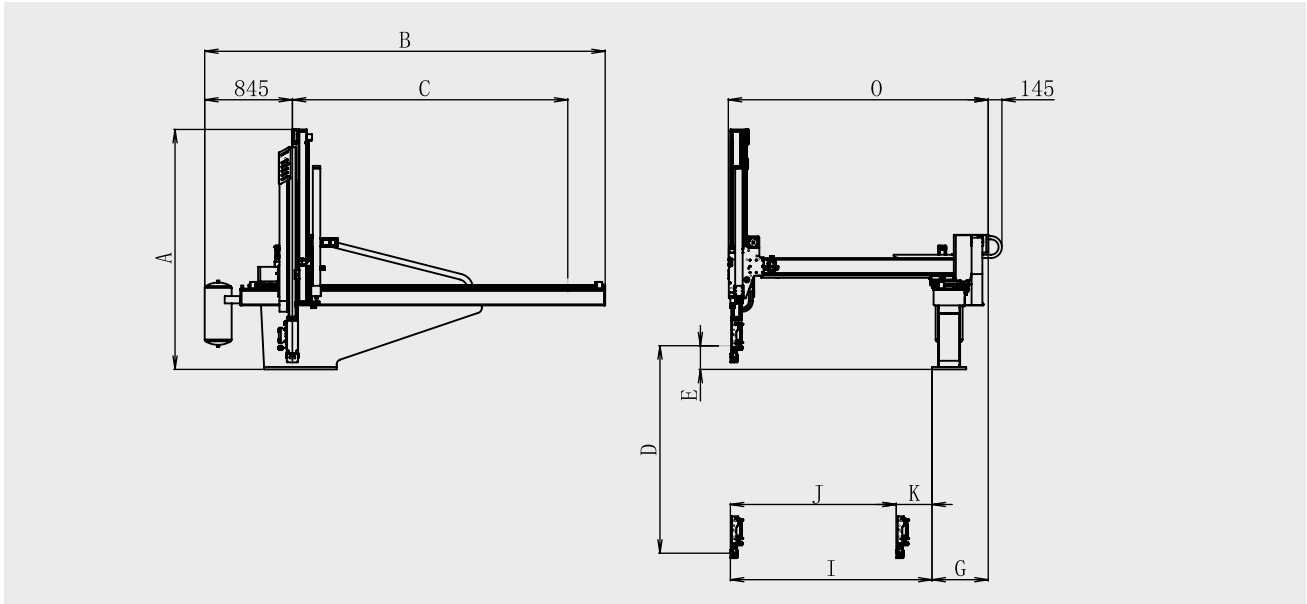


### 型式 MODEL

单位 UNIT

MBW-170

电源 Power Source	V	AC 220±10% 50/60Hz
最大消费电力 Max Power Consumption	KW	2.4
使用气压 Air Pressure	Mpa	0.5~0.7
空气消费量 Air Consumption	NI/cycle	26
驱动方式 Drive System	---	伺服马达 / AC Servo Motor
姿势 (气缸) Posture (Air Cylinder)	---	90°固定 / 90°Fixed
■ 气缸推力 (气压0.5MPa时) Air Cylinder Driving Force (Air Pressure at 0.5MPa)		
最大可搬重量 Max.Load	Kg	20【含夹具重量 / Incl Chuck Weight】
姿势力矩 Posture Torque	N·m	57.7
■ 行程 Stroke		
主臂上下 Main-arm Vertical	mm	1700/2000
副臂上下 Sub-arm Vertical	mm	---
前后 Crosswise	mm	275~1875
走行 Traverse	mm	2500/3000
■ 本体重量 Net Weight		
本体 Main Body	Kg	1245~1380
操作盒 Pendant	Kg	1.6



**外形尺寸 OUTER DIMENSIONS**

**MBW-170**

**选项功能 OPTION FUNCTION**

A	总高 Overall height	2320(2440)mm
B	总长 Overall length	3700(4180)mm
C	走行行程 Traverse stroke	2500(3000)mm
D	主臂上下行程 Main-arm vertical stroke	1700(2000)mm
E	主臂上下待机 Main-arm vertical standby	350mm
F	夹具安装有效空间 Bottom of crosswise to chuck mount position	---
G	底座里侧面-箱体末端 Base side face-Box end	710mm
H	副臂上下待机 Sub-arm Vertical standby	---
I	主臂前进最大值 Main-arm reach max	1875mm
J	主臂前进最大行程 Main-arm crosswise stroke max	1600mm
K	主臂前后待机最小值 Main-arm crosswise standby min	275mm
L	主副臂接近最小值 Main/Sub-arm proximity min	---
M	副臂前进最大行程 Sub-arm crosswise stroke max	---
N	副臂前后待机最小值 Sub-arm crosswise standby min	---
O	前后臂末端-箱体末端 Crosswise arm end-Box end	2475mm

- ◆ 夹具内剪刀回路  
Air nipper in chuck circuit
- ◆ NT剪切·可动侧  
NT gate cutting on crossmember of moving
- ◆ 吸着确认4回路  
Additional vacuum sensing unit ( 4 circuits )
- ◆ 制品夹取4回路  
Product gripping 4 circuits
- ◆ 上升途中闭模  
Mold close during ascend
- ◆ 回转单元  
Rotation unit
- ◆ 顶针后退连动  
Ejector return link
- ◆ 欧规12  
EUROMAP12
- ◆ 欧规67  
EUROMAP 67

- 当尺寸C是2500mm时，尺寸B为3700mm
- when dimension C is 2500mm , B is 3700mm

- 当尺寸C是3000mm时，尺寸B为4180mm
- when dimension C is 3000mm , B is 4180mm

- 当尺寸D是1700mm时，尺寸A为2320mm
- when dimension D is 1700mm , A is 2320mm

- 当尺寸D是2000mm时，尺寸A为2440mm
- when dimension D is 2000mm , A is 2440mm

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